## Degrees of d.c.e. reals

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#### Abstract

A real is called c.e. if it is the halting probability of a prefix free Turing machine. Equivalently, a real is c.e. if it is left computable in the sense that  $L(\alpha) = \{q \in \mathbb{Q} : q \leq \alpha\}$  is a computably enumerable set. The natural field formed by the c.e. reals turns out to be the field formed by the collection of reals of the form  $\alpha - \beta$  where  $\alpha$  and  $\beta$  are c.e. reals. While c.e. reals can only be found in the c.e. degrees, Zheng has proven that there are  $\Delta_2^0$  degrees that are not even n-c.e. for any n and yet contain d.c.e. reals.

In this paper we will prove that every  $\omega$ -c.e. degree contains a d.c.e. real, but there are  $\omega+1$ -c.e. degrees and, hence  $\Delta_2^0$  degrees, containing no d.c.e. real.

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### 1 Introduction

The central interest in classical computability theory has been the understanding the computational complexity of sets of *positive integers*, yet, even in the original paper of Turing [15], a central topic is interest in effectiveness considerations for *reals*. Of particular interest to computable analysis (e.g. Weihrauch [16]) and to algorithmic information theory (e.g. Li-Vitanyi [11]), is the collection of *computably enumerable reals*.

A real  $\alpha$  is computably enumerable<sup>1</sup> if we can effectively generate it from below. That is, the left cut  $L(\alpha) = \{q \in \mathbb{Q} : q \leq \alpha\}$  forms a c.e. set. Equivalently, a real is c.e. if there is a computable sequence of rationals  $\{q_i : i \in \mathbb{N}\}$  with  $q_{i+1} \geq q_i$  converging to  $\alpha$ . If we can effectively compute the radius of convergence, then the real is computable, in the sense that we can compute effectively the n-th bit of its dyadic expansion. Finally, for interest in Kolmogorov complexity, a real is c.e. iff it is the measure of the domain of a prefix-free Turing<sup>2</sup> machine; that is, a halting probability. If M is a universal prefix-free the real obtained by this is called  $\Omega$ , Chaitin's halting probability, and is definitely not computable because it has no such converging sequence. In fact, whilst the easiest way to generate a c.e. real is to take a c.e. set W and let  $\alpha = .W$ , the real whose dyadic expansion if the characteristic function of W, it is not hard to see that  $\Omega$  is not even in this form.

Various authors have contributed to the study of the collection of c.e. reals. See [3, 4, 5, 6, 7, 16, 17].

However, it is clear the the collection of c.e. reals do not behave well algebraically since, for instance,  $1-\Omega$  is not c.e.. Because of this, in [1], Ambos-Spies, Weihrauch and Zheng investigated the collection of the differences of c.e. reals,  $\mathcal{D} = \{\alpha - \beta : \alpha, \beta \text{ c.e. reals}\}$  and proved that  $\mathcal{D}$  is closed under the arithmetic operations, and hence forms a field. We call reals in  $\mathcal{D}$  d.c.e. reals. The following proposition gives an analytical characterization of d.c.e. reals:

**Proposition 1** (Ambos-Spies, Weihrauch and Zheng [1]) A real number x

<sup>&</sup>lt;sup>1</sup>We remark that there have been a host of other names for this class including the *left computable*, *left computably enumerable*, *lower semi-computable*, etc reals.

<sup>&</sup>lt;sup>2</sup>Recall that a Turing machine M is called prefix-free iff for all  $\sigma$ ,  $\tau$  if  $\sigma \prec \tau$  and  $M(\sigma) \downarrow$ , then  $M(\tau) \uparrow$ . Such machines have measurable domains with the standard measure on  $2^{\omega}$ , being  $\mu(\{\alpha \in 2^{\omega} : \sigma \prec \alpha\}) = 2^{-|\sigma|}$ .

is d.c.e. iff there is a computable sequence  $(x_s)$  of rational numbers which converges to x such that  $\sum_{s\in\mathbb{N}} |x_s - x_{s+1}| \le c$  for a constant c.

We remark that because of Theorem ??, we can easily see that the field of d.c.e. reals is in fact a real closed field. The proof is simple. If x is d.c.e. and  $(x_s)$  converges to x such that  $\sum |x_s - x_{s+1}|$  is finite, then the sequence  $(\sqrt{x_s})$  converges to  $\sqrt{x}$  and the sum  $\sum |\sqrt{x_s} - \sqrt{x_{s+1}}|$  is finite too. That is  $\sqrt{x}$  is d.c.e..

However, Zheng has shown that the class of d.c.e. reals is not closed under computable monotone functions.

Say that a real  $\delta$  is proper d.c.e. if  $\delta$  is d.c.e. and does not equal to any c.e. real. An easy example of a proper d.c.e real is found by taking  $\delta$  as a binary expansion of a proper 2-c.e. set, or a proper d.c.e. set, since a 2-c.e. set can be regarded as the difference of two c.e. sets. We recall the definition of the boolean algebra of n-c.e. sets.

**Definition 2** (Ershov [8, 9]) The difference hierarchy is defined as follows:

- (i) A set  $A \subseteq \omega$  is called *n-computably enumerable* (*n-c.e.*, for short), if there is a computable function f such that for all  $x \in \omega$ ,
  - (a) f(x,0) = 0,
  - (b)  $\lim_{s} f(x,s) \downarrow = A(x)$ , and
  - (c)  $|\{s+1 \mid f(x,s) \neq f(x,s+1)\}| \leq n$ .
- (ii) A set  $A \subseteq \omega$  is  $\alpha$ -computably enumerable ( $\alpha$ -c.e., for short) relative to a computable system  $\mathcal{S}$  of notations for  $\alpha$  if and only if there is a partial computable (p.c.) function f such that for all k, A(k) = f(k, b), where b is the  $\mathcal{S}$ -least notation x such that f(k, x) converges.

By Definition 2, a set  $A \subseteq \omega$  is  $\omega$ -c.e. if and only if there are two computable functions f(x, s), g(x) such that for all  $x \in \omega$ ,

- (a) f(x,0) = 0,
- (b)  $\lim_{s} f(x,s) \downarrow = A(x)$ , and
- (c)  $|\{s+1 \mid f(x,s) \neq f(x,s+1)\}| < q(x)$ .

The following simple fact is from Arslanov [2].

**Proposition 3** (Arslanov [2]) Let A be any  $\omega$ -c.e. set. Then there exists an  $\omega$ -c.e. set  $B \equiv_T A$  and a computable functions f(x,s) such that for all  $x \in \omega$ ,

- (a) f(x,0) = 0,
- (b)  $\lim_s f(x,s) \downarrow = B(x)$ , and
- (c)  $|\{s+1 \mid f(x,s) \neq f(x,s+1)\}| \leq x$ .

Here is a simple proof of this fact, which was surely known before it was stated by Arslanov. Suppose that A is  $\omega$ -c.e. with at most g(x) mind changes for each x. Without loss of generality we can suppose that g is an increasing computable function. Now define B by putting  $g(x) \in B$  iff  $x \in A$ . Then  $B \equiv_m A$  and B is  $\omega$ -c.e. via the identity function.

It is easy to see that for any n-c.e. set A, the binary expansiony of A is a d.c.e. real. The converse is not true. Zheng [18] constructed a d.c.e. real not contained in any  $\omega$ -c.e. degree.

Additionally, in section 2, we prove that any  $\omega$ -c.e. degree contains a d.c.e. real.

**Theorem 4** Let **a** be any  $\omega$ -c.e. degree, then **a** contains a d.c.e. real.

In view of Zheng's result, and that of Ho [10] that every  $\Delta_2^0$  real is the limit of a computable sequence of rationals, it even seemed reasonable that perhaps every  $\Delta_2^0$  degree contained a d.c.e. real. The answer is no. In section 3, we construct a  $\Delta_2^0$  set (indeed, an  $\omega + 1$ -c.e. set) not Turing equivalent to any d.c.e. real.

**Theorem 5** There are  $\Delta_2^0$  degrees containing no d.c.e. real.

We remark that the method of proof for Theorem 5 is new and may well have other applications.

Our notation and terminology are standard and generally follow Soare [14]. For a set A, we use  $A_s$  to denote the set of elements in A at the end of stage s. For a given partial computable (p.c.) functional  $\Phi$ , and a set A, the use function  $\varphi^A$  is bounded by stages. We also assume that if  $\varphi^{A_s}_s(x)$  converges, and y < x, then  $\varphi^{A_s}_s(y)[s]$  also converges. Seta are identified with their characteristic functions. Finally,  $\Delta$  denotes symmetric difference.

## 2 Every $\omega$ -c.e. degree contains a d.c.e. real

The proof of Theorem 4 is seperated into two parts. First, we prove that if the bounding function does not increase too fast, then the binary expansionary of the corresponding set is a d.c.e. real.

**Lemma 6** Let A be any  $\omega$ -c.e. set, and f, g be two functions given in Definition 2. If  $\sum_{x \in \mathbb{N}} g(x) \cdot 2^{-x}$  is bounded, then A is a d.c.e. real.

**Proof:** Let c be a constant such that  $\sum_{x \in \mathbb{N}} g(x) \cdot 2^{-x} \leq c$ . W.l.o.g., suppose that  $|A_{s+1}\Delta A_s| \leq 1$  for any s. Then  $\{0.A_s : s \in \mathbb{N}\}$  is a computable sequence of rational numbers converging to 0.A and

$$\sum_{s \in \mathbb{N}} |0.A_s - 0.A_{s+1}| = \sum_{s \in \mathbb{N}} \{2^{-x} : x \in A_{s+1} \Delta A_s\} = \sum_{x \in \mathbb{N}} 2^{-x} \cdot g(x) \le c.$$

By Propostion 1, 0.A is d.c.e..

Now we combine Lemma 6 with Propostion 3 to give a proof of Theorem 4.

**Proof of Theorem 4**: Let **a** be any  $\omega$ -c.e. Turing degree and  $A \in \mathbf{a}$  be an  $\omega$ -c.e. set. By Proposition 3, there is an  $\omega$ -c.e. set B Turing equivalent to A and a computable function f satisfying (a)-(c) in Proposition 3. Since  $\sum_{n\in\mathbb{N}} n \cdot 2^{-n} \leq 2$  is bounded, by Lemma 6, 0.B is a d.c.e. real. Therefore, **a** contains a d.c.e real.

We remark here that Theorem 4 can also be proved in a constructive way. That is, given A as an  $\omega$ -c.e. set, we can construct two c.e. reals  $\alpha$ ,  $\beta$  such that  $\alpha - \beta$  is Turing equivalent to A. The main idea of the construction is as follows.

Let f, g be two computatable functions satisfying the following conditions:

- (a) f(x,0) = 0,
- (b)  $\lim_{s} f(x,s) \downarrow = A(x)$ , and
- (c)  $|\{s: f(x,s) \neq f(x,s+1)\}| \leq g(x)$ .

W.l.o.g., suppose that for any  $s \in \mathbb{N}$ ,  $|\{x : f(x,s) \neq f(x,s+1)\}| \leq 1$ . Let  $A_s = \{x : f(x,s) = 1\}$ . By our assumption on f, for any  $s \in \mathbb{N}$ ,  $|A_s \Delta A_{s+1}| \leq 1$ . Define a function h such that  $h(n) = \sum_{i < n} (g(n) + 2)$ . Obviously, h is computable. We describe the approximations of  $\alpha$  and  $\beta$  as follows.

First, let  $\alpha_0 = \sum_{n \in \mathbb{N}} 2^{-h(n)}$ ,  $\beta_0 = 0$ .  $\alpha_{s+1}, \beta_{s+1}$  are defined as follows:

$$\alpha_{s+1} = \begin{cases} \alpha_s + 2^{-(h(n+1)-1)} & \text{if } A_s = A_{s+1} \cup \{n\}; \\ \alpha_s & \text{otherwise.} \end{cases}$$

$$\beta_{s+1} = \begin{cases} \beta_s + 2^{-(h(n+1)-1)} & \text{if } A_{s+1} = A_s \cup \{n\}; \\ \beta_s & \text{otherwise.} \end{cases}$$

Then  $\alpha = \lim_{s \to \infty} \alpha_s$  and  $\beta = \lim_{s \to \infty} \beta_s$  are both c.e. and hence  $\alpha - \beta$  is d.c.e.. It is easy to see that for any n and s, the following hold:

$$A_s(n) = 0 \iff (\alpha_s - \beta_s) \upharpoonright [h(n), h(n+1)) = 100 \cdots 00$$
  
 $A_s(n) = 1 \iff (\alpha_s - \beta_s) \upharpoonright [h(n), h(n+1)) = 011 \cdots 11.$ 

Therefore,

$$A(n) = 0 \iff (\alpha - \beta) \upharpoonright [h(n), h(n+1)) = 100 \cdots 00$$
  
$$A(n) = 1 \iff (\alpha - \beta) \upharpoonright [h(n), h(n+1)) = 011 \cdots 11.$$

 $\alpha - \beta$  is Turing equivalent to A.

# 3 A $\Delta_2^0$ degree containing no d.c.e. reals

In this section, we prove that not every  $\Delta_2^0$ -Turing degree contains a d.c.e. real. To this end, we construct a  $\Delta_2^0$ -set A which is not Turing equivalent to any d.c.e. real. That is, A is constructed to satisfy the following requirements:

$$\mathcal{R}_e: A \neq \Phi_e^{\alpha_e - \beta_e} \ \lor \ \alpha_e - \beta_e \neq \Psi_e^A \tag{1}$$

where  $\{\langle \Phi_e, \Psi_e, \alpha_e, \beta_e \rangle : e \in \mathbb{N}\}$  is an effective enumeration of all 4-tuples  $\langle \Phi, \Psi, \alpha, \beta \rangle$ ,  $\Phi, \Psi$  computable functionals, and  $\alpha, \beta$  c.e. reals. Say that requirement  $\mathcal{R}_e$  has priority higher than  $\mathcal{R}_{e'}$  if e < e'.

A is constructed as a  $\Delta_2^0$  set by stages. Let  $A_s$  be the approximation of A at the end of stage s. Then  $A = \lim_{s\to\infty} A_s$ . We now describe a

strategy satisfying a single requirement. First we define the length function of agreement for  $\mathcal{R}_e$  at stage s as follows:

$$l(e,s) = \max\{x : A_s(x) = \Phi_{e,s}^{\alpha_{e,s} - \beta_{e,s}}(x) \& (\alpha_{e,s} - \beta_{e,s}) \upharpoonright \varphi_{e,s}(x) = \Psi_{e,s}^{A_s} \upharpoonright \varphi_{e,s}(x)\},\$$

where  $\varphi_e$  is the use function of the functional  $\Phi_e$ . Our strategy will ensure that l(e, s) is bounded during the construction, and hence  $\mathcal{R}_e$  is satisfied.

We first choose a witness x as a big number and wait for a stage s with l(e,s) > x. Put x into A, and wait for another stage s' > s with l(e,s') > x. If there is no such a stage, then  $\mathcal{R}_e$  is satisfied obviously. Otherwise, we have that  $\alpha - \beta$  changes below  $\varphi_{e,s}(x)$  between stages s and s'. That is,  $\Psi_e^A \upharpoonright \varphi_{e,s}(x)$  have changes between s and s'. Note that the only small number enumerated into A between s and s' is x, so by taking x out of A, we recover the computations  $\Psi_e^A \upharpoonright \varphi_{e,s}(x)$  to  $\Psi_{e,s}^{A_s} \upharpoonright \varphi_{e,s}(x)$ , and we have a temporary disagreement between  $(\alpha_e - \beta_e) \upharpoonright \varphi_{e,s}(x)$  and  $\Psi_e^A \upharpoonright \varphi_{e,s}(x)$ . If  $(\alpha_e - \beta_e) \upharpoonright \varphi_{e,s}(x)$  don't change later, then by preserving A on  $\psi_{e,s}(\varphi_{e,s}(x))$ , we will have

$$(\alpha_e - \beta_e) \upharpoonright \varphi_{e,s}(x) \neq \Psi_e^A \upharpoonright \varphi_{e,s}(x),$$

and  $\mathcal{R}_e$  is satisfied again. By iterating such a procedure, we put x into A and take x out of A alternatively, trying to get a disagreement between A and  $\Phi_e^{(\alpha_e-\beta_e)}$  or between  $(\alpha_e-\beta_e)\upharpoonright \varphi_{e,s}(x)$  and  $\Psi_e^A \upharpoonright \varphi_{e,s}(x)$ . It is easy to check that if  $(\alpha_e-\beta_e)\upharpoonright \varphi_{e,s}(x)$  changes only finitely often, then we can get the wanted disagreement eventually, and  $\mathcal{R}_e$  is satisfied. However,  $(\alpha_e-\beta_e)\upharpoonright \varphi_{e,s}(x)$  may change infinitely often, as pointed out below, even though both  $\alpha_e \upharpoonright \varphi_{e,s}(x)$  and  $\beta_e \upharpoonright \varphi_{e,s}(x)$  settle down after a stage large enough.

Fix i.  $(\alpha_e - \beta_e)(i)$  can be changed by changes of  $\alpha_e(j)$  or  $\beta_e(j)$ , where j > i. For example, let

$$\alpha_{e,1} = \alpha_{e,2} = 0.101w0$$
,  $\beta_{e,1} = 0.100w1$  and  $\beta_{e,2} = 0.100w0$ .

for some  $w \in \{0,1\}^n$  and  $n \in \mathbb{N}$ . Then we have

$$\alpha_{e,1} - \beta_{e,1} = 0.0010 \underbrace{1 \cdots 1}_{n} 1$$
 and  $\alpha_{e,2} - \beta_{e,2} = 0.0011 \underbrace{0 \cdots 0}_{n} 0$ .

The change of  $\beta_e(n+4)$  from 1 to 0 leads to the change of  $(\alpha_e - \beta_e)(4)$  from 1 to 0. We call such a change of  $\alpha_e - \beta_e$  as a "nonlocal-disturbance". Note that  $(\alpha_e - \beta_e)(4)$  can be changed infinitely often by these nonlocal-disturbances since we have infinitely many such ws. Fortunately, if such a "nonlocal-disturbance" happens, then the corresponding segments of  $\alpha_e - \beta_e$  will be in quite simple forms. This is summarized below:

**Proposition 7** Let  $\alpha^j = 0.a_1^j a_2^j \cdots a_n^j$ ,  $\beta^j = 0.b_1^j b_2^j \cdots b_n^j$  and  $\alpha^j - \beta^j = 0.c_1^j c_2^j \cdots c_n^j$  for j = 0, 1. If there are numbers  $i < k \le n$  such that  $c_i^0 \ne c_i^1$ , and  $a_t^0 = a_t^1$ ,  $b_t^0 = b_t^1$  for all  $t \le k$ . Then, there is a  $j \in \{0, 1\}$  such that

$$c_i^j c_{i+1}^j \cdots c_k^j = 011 \cdots 1$$
 &  $c_i^{1-j} c_{i+1}^{1-j} \cdots c_k^{1-j} = 100 \cdots 0.$  (2)

Now let's turn back to consider  $(\alpha_e - \beta_e) \upharpoonright \varphi_{e,s}(x)$ . Suppose that both  $\alpha_e \upharpoonright \varphi_{e,s}(x)$  and  $\beta_e \upharpoonright \varphi_{e,s}(x)$  do not change after a stage large enough,  $s_1$  say, then by Proposition 7, the initial segment  $(\alpha_e - \beta_e) \upharpoonright \varphi(x)$  can have only one of two different forms:  $0.w011 \cdots 1$  or  $0.w100 \cdots 0$  for some fixed binary word w. It leads us to use two-attackers to satisfy  $\mathcal{R}_e$ , instead of using a single attacker. That is, at stage s', instead of taking x out of A, we put x-1 into A and wait for a stage s'' > s' with l(e, s'') > x. At stage s'', we take x-1 and x out of A, and wait for a stage s''' > s'' with l(e, s''') > x. As a consequence,  $A \upharpoonright \psi_e(\varphi_{e,s}(x))$  is recovered to that of stage s. Now we have three uses of  $\varphi_e(x)$ , i.e.,  $\varphi_{e,s}(x)$ ,  $\varphi_{e,s'}(x)$ , and  $\varphi_{e,s''}(x)$ . At stage s'''+1, we will have  $(\alpha_{e,s'''} - \beta_{e,s'''}) \upharpoonright \varphi_{e,s}(x) = (\alpha_{e,s} - \beta_{e,s}) \upharpoonright \varphi_{e,s}(x)$ . As in stage s, we put s into s again. We call the procedure between s and s'''+1 a complete cycle.

Let k be the maximum among  $\varphi_{e,s}(x)$ ,  $\varphi_{e,s'}(x)$ , and  $\varphi_{e,s''}(x)$ . Then in a complete cycle  $(\alpha_e - \beta_e) \upharpoonright k$  has three different forms. By Proposition 7, in each complete cycle,  $\alpha_e$  or  $\beta_e$  must have a change below k. Since  $\alpha_e$ ,  $\beta_e$  are both c.e., we can assume that after a stage t large enough,  $\alpha_e \upharpoonright k$  and  $\beta_e \upharpoonright k$  don't change anymore, and therefore, after t, no cycle can be complete. As a consequence, one of the combinations of A(x-1) and A(x), 00, 01, or 11, satisfies the requirement  $\mathcal{R}_e$ .

We describe the whole construction of A below.

#### Construction of A

During the construction, say that a requirement  $\mathcal{R}_e$  requires attention at stage s+1 if  $x_e$  is defined and  $l(e,s) > x_e$ . When we initialize a requirement  $\mathcal{R}_e$ , we undefine all parameters associated with it.

Stage s = 0: Do nothing.

Stage s + 1: If no requirement requires attention at stage s + 1, then choose a least e such that  $x_e$  is not defined and define  $x_e = s + 2$ .

Otherwise, let  $\mathcal{R}_e$  be the requirement of the highest priority requiring attention and define

$$A_{s+1}(x_e - 1)A_{s+1}(x_e) = \begin{cases} 01 & \text{if } A_s(x_e - 1)A_s(x_e) = 00; \\ 11 & \text{if } A_s(x_e - 1)A_s(x_e) = 01; \\ 00 & \text{if } A_s(x_e - 1)A_s(x_e) = 11. \end{cases}$$
(3)

Initialize all requirements with lower priority, and declare that  $R_e$  receives attention at stage s + 1.

This completes the construction.

We now verify that A constructed above satisfies all the requirements. We only need to prove the following lemma.

**Lemma 8** For any  $e \in \mathbb{N}$ ,  $\mathcal{R}_e$  requires and receives attention finitely often.

**Proof:** We prove Lemma 8 by induction on e. Assume that, for any i < e,  $\mathcal{R}_i$  requires and receives attention only finitely often. Let  $s_0$  be the least stage after which no requirement  $\mathcal{R}_i$ , i < e, requires attention. By the choice of  $s_0$ ,  $R_e$  is initialized at stage s'. Let  $s_1 > s_0$  be the stage at which  $x_e$  is defined. Since  $\mathcal{R}_e$  cannot be initialized after stage  $s_0$ ,  $s_0$  cannot be canceled afterwards. We prove below that after a stage large enough,  $s_0 > s_1$  say,  $s_0$  does not require attention anymore, and hence  $s_0$  cannot exceed  $s_0$  for  $s_0 > s_0$ ,  $s_0$  is satisfied.

For a contradiction, suppose that after stage  $s_1$ , there are infinitely many stages  $t_0 + 1$ ,  $t_1 + 1$ ,  $t_2 + 1$ ,  $\cdots$  at which  $\mathcal{R}_e$  requires attention. Then, at stage  $t_0 + 1$ , we have  $l(e, t_0) > x_e$ ,  $A_{t_0}(x_e - 1)A_{t_0}(x_e) = 00$ ,  $A_{t_0+1}(x_e - 1)A_{t_0+1}(x_e) = 01$ . By the choice of  $s_0$ , no requirement with higher priority can put numbers smaller than  $\psi_{e,t_0}(\varphi_{e,t_0}(x_e))$  into A. Since all requirements with lower priority are initialized at stage  $t_0 + 1$ , when these requirements receive attention after  $t_0 + 1$ , the numbers they put into A or take out of A are all larger than  $t_0$ , and hence larger than  $\psi_{e,t_0}(\varphi_{e,t_0}(x_e))$ . Therefore, the computations  $\Psi_{e,t_0}^{A_{t_0}}(\varphi_{e,t_0}(x_e))$  can only be changed by  $\mathcal{R}_e$  itself by changing  $A(x_e - 1)$  or  $A(x_e)$ . Thus, by a simple induction, we have for all  $n \in \mathbb{N}$ ,

$$A_{t_0} \upharpoonright \psi_{e,t_0}(\varphi_{e,t_0}(x_e)) = A_{t_{3n}} \upharpoonright \psi_{e,t_0}(\varphi_{e,t_0}(x_e))$$

because  $A(x_e - 1)A(x_e)$  changes always in the order  $00 \to 01 \to 11 \to 00$ . Therefore,

$$(\alpha_{e,t_{3n}} - \beta_{e,t_{3n}}) \upharpoonright \varphi_{e,t_0}(x_e) = (\alpha_{e,t_0} - \beta_{e,t_0}) \upharpoonright \varphi_{e,t_0}(x_e).$$

This means that the computation  $\Phi_{e,t_{3n}}^{A_{t_{3n}}}(x_e)$  is actually the same as that of  $\Phi_{e,t_0}^{A_{t_0}}(x_e)$ . Similarly, we can prove that the computation  $\Phi_{e,t_{3n+1}}^{A_{t_{3n+1}}}(x_e)$  is the same as that of  $\Phi_{e,t_1}^{A_{t_1}}(x_e)$ , and the computation  $\Phi_{e,t_{3n+2}}^{A_{t_{3n+2}}}(x_e)$  is the same as that of  $\Phi_{e,t_2}^{A_{t_2}}(x_e)$ .

Let  $k = \max\{\varphi_{e,i}(x_e) : i \leq 3\}$ . Choose an n large enough such that  $l(e,t_n) > x_e$ , and

$$\alpha_{e,t_n} \upharpoonright k = \alpha_{e,t} \upharpoonright k$$
 &  $\beta_{e,t_n} \upharpoonright k = \beta_{e,t} \upharpoonright k$ 

for any  $t \ge t_n$ . W.o.l.g., suppose that n = 3m for some m. Then  $A_{t_n}(x_e - 1)A_{t_n}(x_e) = 00$ ,  $A_{t_{n+1}}(x_e - 1)A_{t_{n+1}}(x_e) = 01$ , and  $A_{t_{n+2}}(x_e - 1)A_{t_{n+2}}(x_e) = 11$ . By our choices of  $t_n, t_{n+1}, t_{n+2}$ , we have

$$\Phi_{e,t_n}^{\alpha_{e,t_n}-\beta_{e,t_n}}(x_e-1)\Phi_{e,t_n}^{\alpha_{e,t_n}-\beta_{e,t_n}}(x_e) = 00$$
, and

$$\Phi_{e,t_{n+1}}^{\alpha_{e,t_{n+1}}-\beta_{e,t_{n+1}}}(x_e-1)\Phi_{e,t_{n+1}}^{\alpha_{e,t_{n+1}}-\beta_{e,t_{n+1}}}(x_e)=01.$$

This implies that

$$(\alpha_{e,t_n} - \beta_{e,t_n}) \upharpoonright \varphi_{e,t_n}(x_e) \neq (\alpha_{e,t_{n+1}} - \beta_{e,t_{n+1}}) \upharpoonright \varphi_{e,t_{n+1}}(x_e)$$

and hence  $(\alpha_{e,t_n} - \beta_{e,t_n}) \upharpoonright k \neq (\alpha_{e,t_{n+1}} - \beta_{e,t_{n+1}}) \upharpoonright k$ . By Lemma 7, there exists a binary word w such that  $(\alpha_{e,t_n} - \beta_{e,t_n}) \upharpoonright k$  takes one of the forms  $0.w100 \cdots 0$  and  $0.w011 \cdots 1$ , and  $(\alpha_{e,t_{n+1}} - \beta_{e,t_{n+1}}) \upharpoonright k$  takes the other one. Assume that  $(\alpha_{e,t_n} - \beta_{e,t_n}) \upharpoonright k$  takes the form  $0.w100 \cdots 0$  and  $(\alpha_{e,t_{n+1}} - \beta_{e,t_{n+1}}) \upharpoonright k$  takes the form  $0.w011 \cdots 1$ . By the same argument, since  $(\alpha_{e,t_{n+1}} - \beta_{e,t_{n+1}}) \upharpoonright k$  takes the form  $0.w011 \cdots 1$ , we know that  $(\alpha_{e,t_{n+2}} - \beta_{e,t_{n+2}}) \upharpoonright k$  takes the form  $0.w100 \cdots 0$ . Thus,

$$(\alpha_{e,t_{n+2}} - \beta_{e,t_{n+2}}) \upharpoonright k = (\alpha_{e,t_n} - \beta_{e,t_n}) \upharpoonright k,$$

and hence

$$00 = \Phi_e^{\alpha_e - \beta_e}(x_e - 1)[t_n]\Phi_e^{\alpha_e - \beta_e}(x_e)[t_n] = \Phi_e^{\alpha_e - \beta_e}(x_e - 1)\Phi_e^{\alpha_e - \beta_e}(x_e) = 11.$$

A contradiction. Therefore, after stage  $t_n$ ,  $\mathcal{R}_e$  can require (and hence receive) at most two more times

This ends the proof of Lemma 8.

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